

[illegible]

1. A receiver comprising:

a direction metric determiner which generates direction metrics of each of a set of possible directions of joint movement of at least two fingers of a finger block;

a metric selector which selects one of said direction metrics according to a predetermined criterion; and

a finger adjuster which moves the fingers of said finger block in the directions indicated by said selected direction metric.

2. A receiver according to claim 1, wherein said selected direction metric is the maximal direction metric.

3. A receiver according to claim 1, wherein said finger adjuster moves the fingers of said finger block only if said selected direction metric is the maximal direction metric and exceeds a comparison direction metric by at least a predetermined threshold.

4. A receiver according to claim 1, wherein said finger adjuster includes a redefiner which redefines finger blocks once said fingers have been moved.

5. A receiver according to claim 1, wherein said finger block is formed of two fingers.

6. A receiver according to claim 5, wherein said determiner generates said direction metrics for five different directions of joint movement.

7. A receiver according to claim 5, wherein said determiner generates said direction metrics for six different directions of joint movement.

8. A receiver according to claim 5, wherein said determiner generates said direction metrics for nine different directions of joint movement.
9. A receiver according to claim 1, wherein said finger block is formed of two closely spaced fingers.
- 5 10. A receiver according to claim 9, wherein said closely spaced fingers are  $\frac{7}{8}$  chip apart.
11. A receiver according to claim 1, wherein said finger block is formed of three fingers.
12. A receiver according to claim 1, wherein delays between fingers are set to  
10 be no smaller than  $\frac{7}{8}$  chip.
13. A receiver according to claim 1, wherein said direction metrics are based on power estimation.
14. An article comprising a storage medium having stored thereon instructions, that, when executed by a computing platform, cause the  
15 computing platform to generate a direction metrics of each of a set of possible directions of joint movement of at least to fingers of a finger block, select one of said direction metrics according to a predetermined criterion, and to move the fingers of said finger block in the directions indicated by said selected direction metric.
- 20 15. The article according to claim 14, wherein said selected direction metric is the maximal direction metric.
16. The article according to claim 15, wherein the fingers of said finger block is adjusted only if said selected direction metric is the maximal direction metric and exceeds a comparison direction metric by at least a predetermined  
25 threshold.

17. The article according to claim 14, further having stored instructions which cause the computing platform to redefine the finger blocks.
18. The article according to claim 14, wherein said finger block is formed of two fingers.
- 5 19. The article according to claim 18, wherein said direction metrics are generated for five different directions of joint movement.
20. The article according to claim 18, wherein said direction metrics are generated for six different directions of joint movement.
21. The article according to claim 18, wherein said direction metrics are  
10 generated for nine different directions of joint movement.
22. The article according to claim 14, wherein said finger block is formed of two closely spaced fingers.
23. The article according to claim 22, wherein said closely spaced fingers are 7/8 chip apart.
- 15 24. The article according to claim 14, wherein said finger block is formed of three fingers.
25. The article according to claim 14, wherein delays between fingers are set to be no smaller than 7/8 chip.
26. The article according to claim 14, wherein said step of generating includes  
20 the step of time averaging said direction metrics by summing consecutive direction metrics.
27. The article according to claim 26, wherein said step of time averaging uses a forgetting factor.
28. The article according to claim 14, wherein said direction metrics are based  
25 on power estimation.

29. A method comprising forming a finger block of at least two fingers; and  
jointly tracking the fingers of said finger block.

30. A method according to claim 29, wherein the step of jointly tracking  
comprises the steps of:

5       generating direction metrics of each of a set of possible directions of  
joint movement of the fingers of said finger block;

      selecting one of said direction metrics according to a predetermined  
criterion; and

      moving the fingers of said finger block in the directions indicated by  
10   said selected direction metric.